



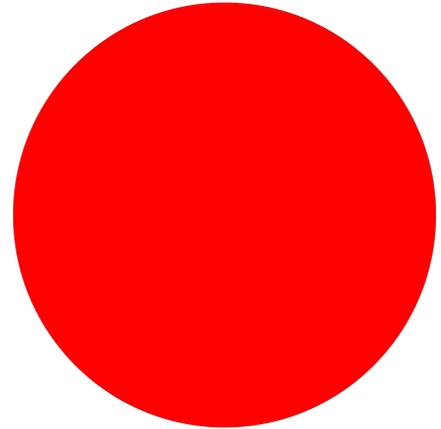
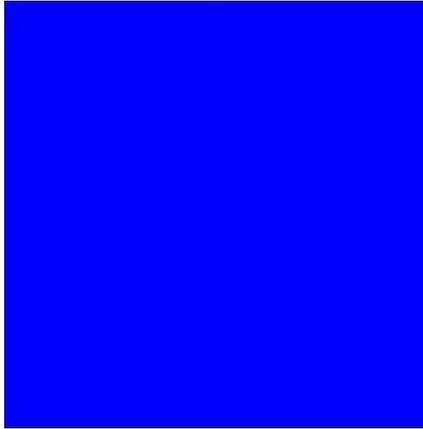
# Computational Models of Cortical Function

Eric Chu and Archana Ram



# Symbols

- Atomic
- Composite

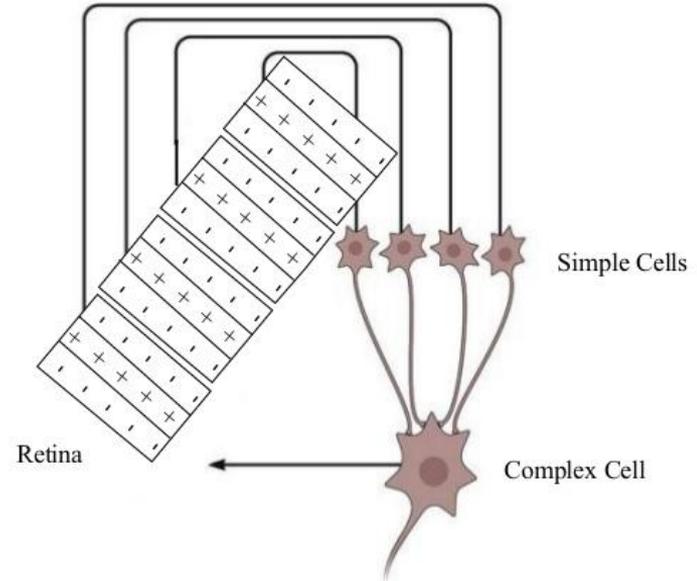


# Symbol encoding

- Unique patterns over sets of neurons

# Visual object representation

- Feature hierarchy
- Simple cells
- Complex cells
- 1+ object in field/background

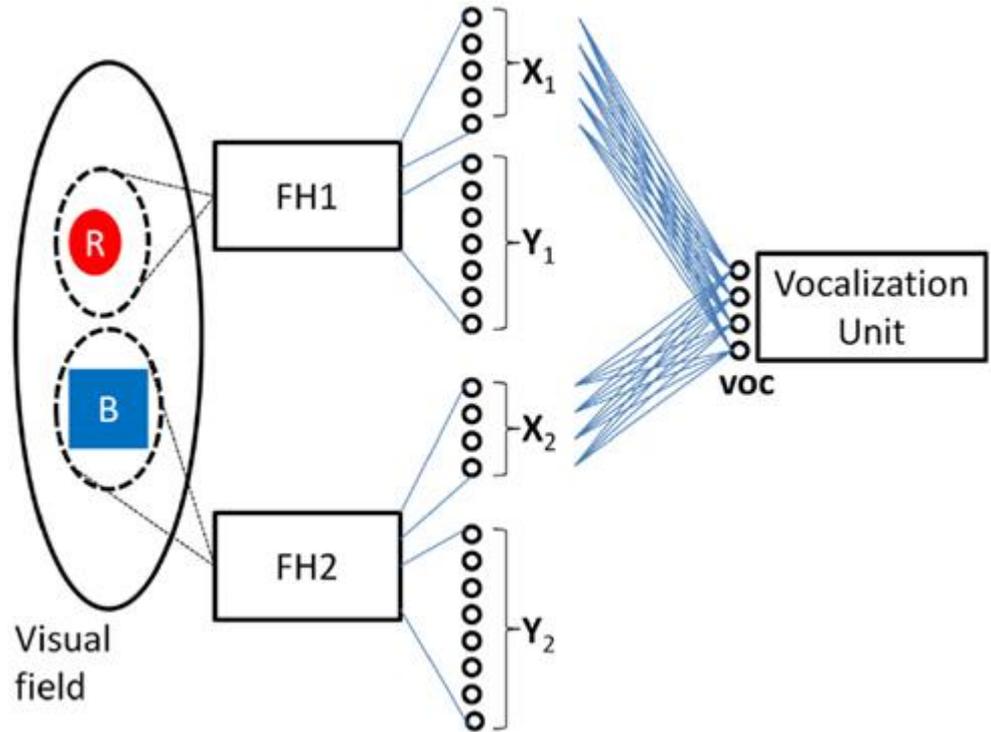


# Variable binding problem

- “red circle and blue square”
- “blue circle and red square”
- Symbol binding
  - *Red* circle
  - “Mary loves John”

# Variable binding in vision

- 2+ visual objects
- Single v. multiple “spotlights”
- Feature hierarchies
- No information generalized
- Role-filler independence



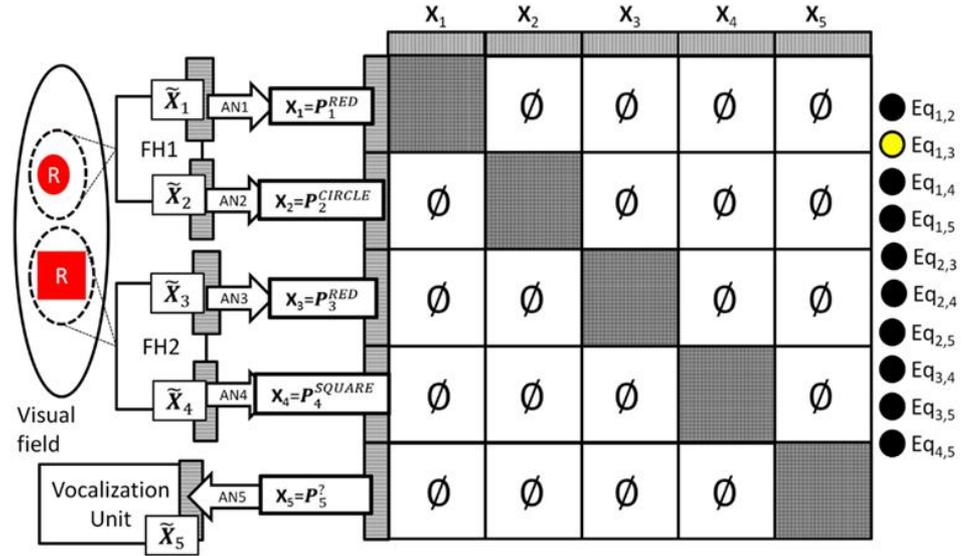
1. How could the larger neural system within this anatomical binding scheme determine whether object 1 and object 2 had the same or different colors (or shapes, etc.)?
2. How could the system vocalize the color of the object represented by  $X_2$  by making use of the associations learned on  $X_1$ ?

# DPAAN solution

- Synchronized training
- “Universal translator” / “universal language”
- Dynamically partitionable autoassociative network

# Perceptual binding with a DPAAAN

- DPAAAN with 5 partitions
- All spotlights lock on object
- Stable patterns are symbols
- "Red," "circle," "square"



1. How could the larger neural system within this anatomical binding scheme determine whether object 1 and object 2 had the same or different colors (or shapes, etc.)?
2. How could the system vocalize the color of the object represented by  $X_2$  by making use of the associations learned on  $X_1$ ?

# Variable binding

- Agent, verb, patient
- Role -> filler
- “I want to table you”
- Pointers

# Physiological evidence

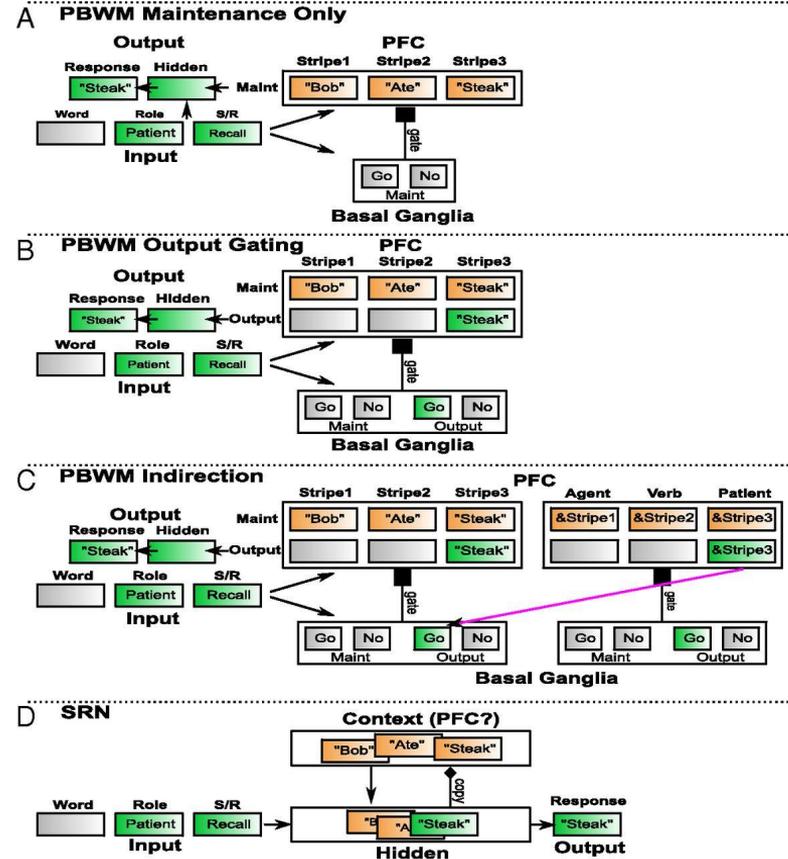
- Stripe-like patches in PFC
  - Inhibitory between, excitatory within
- Project to basal ganglia (BG)
  - Update to encode information
  - Maintain information
  - Output encoded information to drive other processes
- Hierarchy of stripes

# Sentence decoding

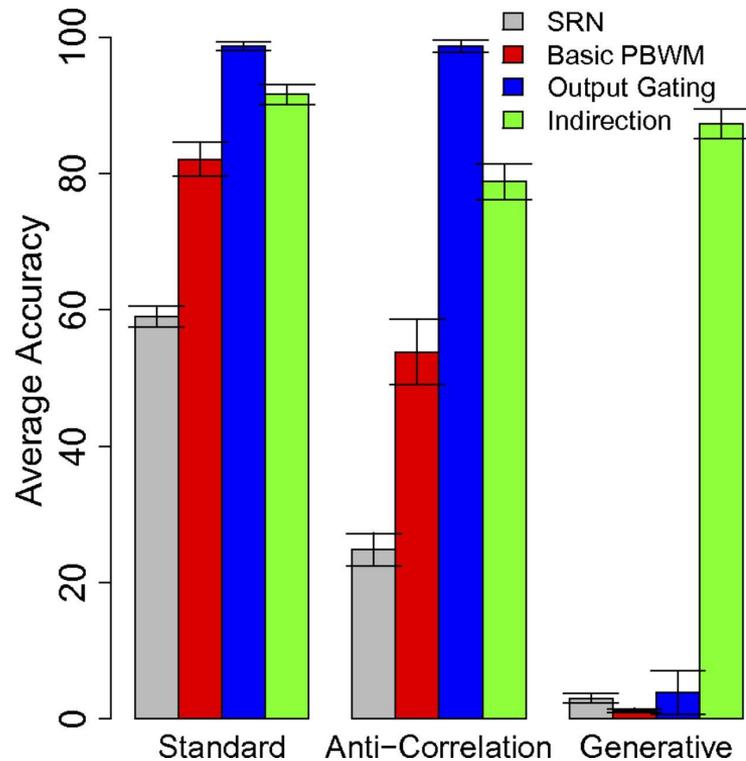
- Agent, verb, patient
  - “She tabled him”
- Presented sentence word-by-word
- Recall
- Anticorrelation

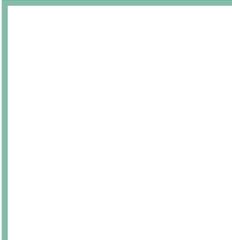
# Models

- Words encoded in separate stripes
- Multiple items in working memory
- 2 networks + output gating
  - Filler-specific
  - Role-specific
- Simple recurrent network



# Model performance





# Neural Random- Access Machines



# Overview

- Architecture can manipulate and dereference **pointers** to an external variable-size random-access memory
- Tested on algorithms involving linked lists and binary trees

# Related Work

- Deep networks with memory, augmented networks
- Examples:
  - Memory Network (Weston 2014): early attempt at explicitly separating memory
    - Tested on question- answering
  - Neural Turing Machine (Graves 2014)
    - Tested on algorithms

# Related Work

- Examples (continued):
  - Attention model (Bahdanau 2014): variants have achieved SOA on machine translation, speech recognition, etc.
  - Grid-LSTM (Kalchbrenner 2015):
    - Tested on Wikipedia character prediction (SOA)
    - Tested on Chinese-to-English translation task
  - Pointer Network (Vinyals 2015): doesn't have writable memory, sort of similar to attention model
    - Tested on computing planar convex hulls, computing Delaunay triangulations, and the Traveling Salesman Problem
  - Stack, queue, dequeue-based models (2015)

# Related Work

- Key-point: depth, size of memory, and number of parameters are no longer confounded and can be altered independently
  - (in contrast to models like LSTM, whose number of parameters grows quadratically with the size of their short term memory)

# Model (No External Memory)

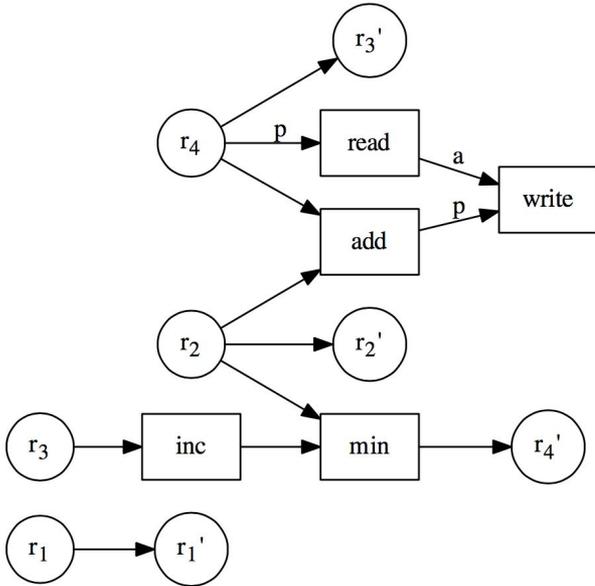
- Neural **controller** (“processor”)
  - Feedforward NN or LSTM
- R **registers**, each represents an integer as a distribution over  $\{0, 1, \dots, M-1\}$ , for some constant M
- Controller interacts with registers through **modules (gates)** such as integer addition and equality test
  - Module  $m_i$ :  $\{0, 1, \dots, M-1\} \times \{0, 1, \dots, M-1\} \rightarrow \{0, 1, \dots, M-1\}$

# Model (No External Memory)

- Performs sequence of timesteps
  - 1) The controller gets some inputs depending on the values of the registers
  - 2) The controller updates its internal state if the controller is an LSTM
  - **3) The controller outputs the description of a “fuzzy circuit” with inputs  $r_1, \dots, r_R$ , gates  $m_1, \dots, m_Q$  and R outputs**
  - 4) The values of the registers are overwritten with the outputs of the circuit

# Model (No External Memory)

- Example “exemplary” circuit for COPY task (step 3):

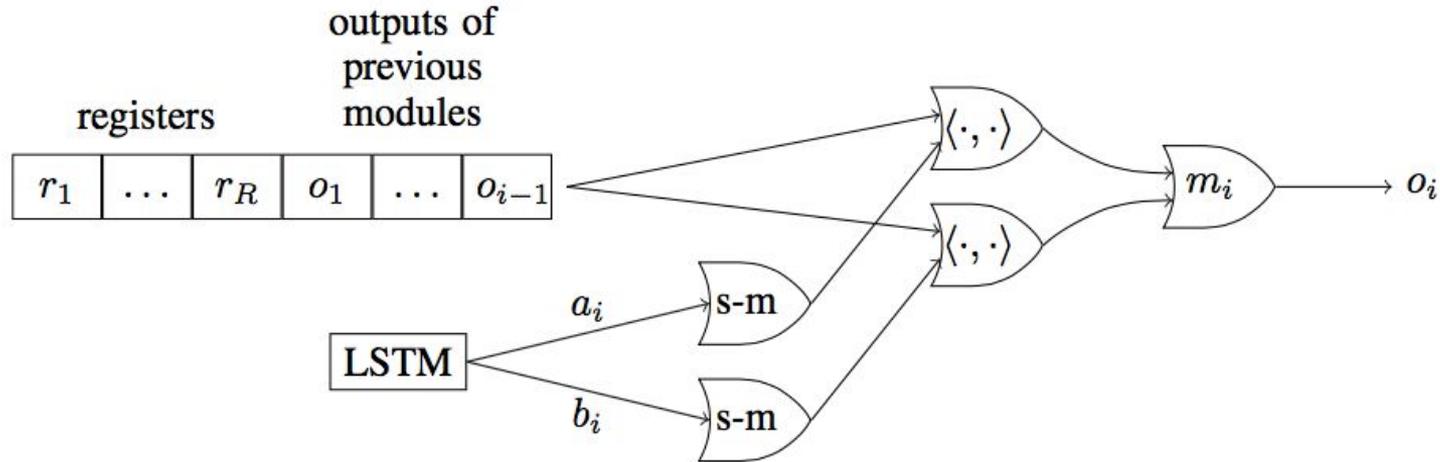


Step	0	1	2	3	4	5	6	7	8	9	10	11	$r_1$	$r_2$	$r_3$	$r_4$	READ	WRITE
1	6	2	10	6	8	9	0	0	0	0	0	0	0	0	0	0	p:0	p:0 a:6
2	6	2	10	6	8	9	0	0	0	0	0	0	0	5	0	1	p:1	p:6 a:2
3	6	2	10	6	8	9	2	0	0	0	0	0	0	5	1	1	p:1	p:6 a:2
4	6	2	10	6	8	9	2	0	0	0	0	0	0	5	1	2	p:2	p:7 a:10
5	6	2	10	6	8	9	2	10	0	0	0	0	0	5	2	2	p:2	p:7 a:10
6	6	2	10	6	8	9	2	10	0	0	0	0	0	5	2	3	p:3	p:8 a:6
7	6	2	10	6	8	9	2	10	6	0	0	0	0	5	3	3	p:3	p:8 a:6
8	6	2	10	6	8	9	2	10	6	0	0	0	0	5	3	4	p:4	p:9 a:8
9	6	2	10	6	8	9	2	10	6	8	0	0	0	5	4	4	p:4	p:9 a:8
10	6	2	10	6	8	9	2	10	6	8	0	0	0	5	4	5	p:5	p:10 a:9
11	6	2	10	6	8	9	2	10	6	8	9	0	0	5	5	5	p:5	p:10 a:9

# Model (No External Memory)

- OK, how are **inputs for module  $m_i$  chosen?** (This defines the circuit)
- For each  $1 \leq i \leq Q$ , ( $Q$  is number of modules),  $i$ -th output determined by  $i$ -th gate according to:

$$o_i = m_i \left( (r_1, \dots, r_R, o_1, \dots, o_{i-1})^T \text{softmax}(a_i), (r_1, \dots, r_R, o_1, \dots, o_{i-1})^T \text{softmax}(b_i) \right)$$



# Model (No External Memory)

- R's are probability distributions, so inputs to  $m_i$  being weighted averages of probability distributions, are also probability distributions
  - How to take probability distribution as input and make output also probability distribution?

$$\forall_{0 \leq c < M} \mathbb{P}(m_i(A, B) = c) = \sum_{0 \leq a, b < M} \mathbb{P}(A = a)\mathbb{P}(B = b)[m_i(a, b) = c].$$

- Q outputs  $o_1, \dots, o_Q$ . Out of values currently in register and outputs ( $\{r_1, \dots, r_R, o_1, \dots, o_Q\}$ ), which should be stored in registers?
  - Controller outputs vectors  $c_i$  in  $R \wedge R + Q$  for each register  $r_i$ ,  $1 \leq i \leq R$

$$r_i := (r_1, \dots, r_R, o_1, \dots, o_Q)^T \mathbf{softmax}(c_i).$$

- $\mathbf{softmax}(c_i)$  just picks out which value to store

# Controller's Inputs

- For each register, controller (NN or LSTM) receives  $P(r_i = 0)$  (as opposed to entire distribution)
- Motivation:
  - Decouples memory size from  $M$
  - Limits amount of info available to controller, so problem is solved by modules and not controller (separation of duty)

# Memory Tape (Pointers!)

- OK, what we have right now can do LIMITED sequence-to-sequence transformation
  - 1) Initialize the registers with input sequence
  - 2) Train the model to produce the desired output sequence in its registers after a given number of timesteps
- PROBLEM: inability to generalize to longer sequences
  - length of sequence model can process is equal to number of registers
- SOLUTION:
  - Variable-size memory tape: **M memory cells**, each which stores a distribution over the set  $\{0,1,\dots,M-1\}$

# Memory Tape (Pointers!)

- **Memory cells** store values (again, probability over  $\{0,1,\dots,M-1\}$ )
- Matrix **M**, value  $M_{i,j}$  is probability that the  $i$ -th cell holds the value  $j$
- Registers can be seen as **fuzzy pointers** (distribution over  $\{0,1,\dots,M-1\}$ ,  $M$  memory cells)
- **READ** module: takes as input a pointer, returns value in memory
  - If input is fuzzy pointer (distribution), then module returns  $(M^T)^*p$  (distribution)
- **WRITE** module: takes as input a pointer  $p$  and a value  $a$ , stores the value  $a$  under the address  $p$  in the memory
  - Fuzzy form with matrices

# Inputs and Outputs Handling

- Model memory initialized with input sequence, expected to produce the output in the memory
- Controller decides whether to continue the execution or finish it, in which case the current state of the memory is treated as the output
  - Controller outputs scalar take sigmoid to get value  $f_i$  in  $[0,1]$  as done or not
  - Can also add maximum timesteps  $T$

# Inputs and Outputs Handling

- **LOSS OF THE MODEL:** NLL of producing the correct output,

$$- \sum_{t=1}^T \left( p_t \cdot \sum_{i=1}^M \log(\mathcal{M}_{i,y_i}^{(t)}) \right)$$

- For an **input-output pair  $\mathbf{x}, \mathbf{y}$  in  $\{0, 1, \dots, M-1\}^M$**  (M length sequence,  $\{0, 1, \dots, M-1\}$  is probability)
- Where **matrix  $\mathbf{M}_{i,j}(\mathbf{t})$**  is probability that the i-th memory cell holds the value j after timestep t
- **Vector  $\mathbf{p}_t$**  = probability that output is produced at exactly the timestep t ( $f_i$  is probability of termination)

$$p_t = f_t \cdot \prod_{i=1}^{t-1} (1 - f_i)$$

# Discretization

- READ takes  $M^2$  time because multiply of  $M$  and  $p$
- Hypothesis (of what happens as the model learns):
  - Model naturally learns solutions in which the distributions of intermediate values have very low entropy. E.g. more like  $[0.01, 0.95, 0.01, 0.01, 0.01]$  than  $[0.2, 0.2, 0.2, 0.2, 0.2]$ 
    - BECAUSE, if this wasn't the case, increased fuzziness would lead to more uncertainty, higher cost
  - **Basically, replace softmax with  $[0, 0, 0, 1, 0, \dots]$  where 1 is at index with argmax**
    - Which speeds up computation
- Superforecasters

# Experiments - Training

Q: Are these empirically-learned engineering tricks plausible in biological brains? How might they be occur?

- Adaptive learning rate optimization techniques
- Gradient clipping
- Curriculum Learning
- Noise
- Enforcing Distribution Constraints

# Experiments - 14 Modules

- ZERO(a,b) = 0
- ONE(a,b) = 1
- TWO(a,b) = 2
- INC(a,b) = (a+1) mod M
- ADD(a,b) = (a+b) mod M
- SUB(a,b) = (a-b) mod M
- DEC(a,b) = (a-1) mod M
- LESS-THAN(a,b) = [a<b]
- LESS-OR-EQUAL-THAN(a,b) = [a<=b]
- EQUALITY-TEST(a,b) = [a=b]
- MIN(a,b) = min(a,b)
- MAX(a,b) = max(a,b)
- READ
- WRITE

# Experiments - Tasks

- Input is given to the network in the memory tape
- Goal is to modify memory
- Final error is  $c/m$ 
  - $c$  is correctly written
  - $m$  is total number of cells that should be modified
- EASY
  - Access, Increment, Copy, Reverse, Swap
- HARD
  - Permutation, ListK, ListSearch, Merge, WalkBST

# Results

- 0% error for all except Merge and WalkBST (error  $\leq 1\%$ )
- Generalizes to inputs longer than the ones seen during training
  - Train complexity: e.g. length of input array  $\leq 20$
  - Tested on inputs up to length  $50^6$
- Discretization hurts performance for all HARD tasks except Permutation
- Question: How long did it take to train?

# Conclusion & Discussion

- Key points for memory networks, augmented networks:
  - Differentiability
  - Ability to handle variable length inputs and outputs
  - Generalizability to longer lengths than training data
  - Probabilistic memory
- What should the evaluation tasks be?